# RR491/RR492 SERIES

The RR491/RR492 frog leg arm vacuum robot realizes high positioning repeatability and highly reliable vacuum partition performance by adopting DDM (vacuum direct drive motor) for the drive section. The full-link arm mechanism realizes highly accurate positioning repeatability.



Image: RR491L300



Image: RR492L400

## Features

- High accuracy
- •Corresponding to ultrahigh vacuum
- High throughput
- •Corresponding to the AWC option (wafer position compensation)

# Main specifications (RR491)

■ Work size to be handled

300 mm works, 200 mm works, and 150 mm works

■ Operating range

Arm length	L300	
Minimum rotation rang	je φ 810	
Distance of reached w	ched work	
center Note 1	770 11111	
Z-axis	70 mm or 140 mm	

### ■ Repeatability

	R direction	± 0.05 mm
	$\theta$ direction	± 0.03°
	Z direction	± 0.05 mm

## Main specifications (RR492)

■ Work size to be handled

 $300\ mm$  works,  $200\ mm$  works, and  $150\ mm$  works

### ■ Operating range

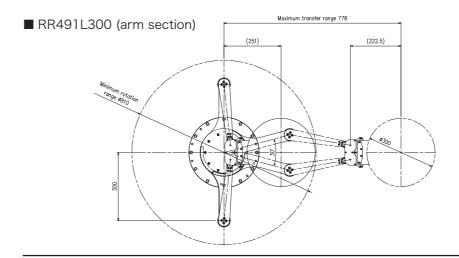
Arm length	L400	
Minimum rotation range	φ 980	
Distance of reached work	1030 mm	
center Note 1	1030 11111	
Z-axis	70 mm or 140 mm	

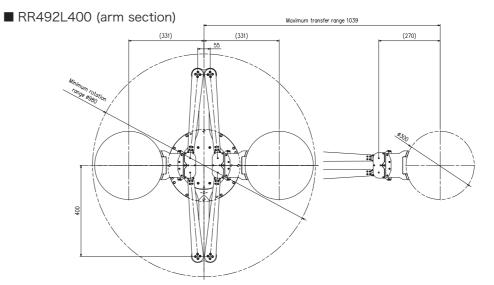
## Repeatability

R direction	± 0.05 mm
$\theta$ direction	± 0.03°
Z direction	± 0.05 mm

Note 1: The distance of reached work center can be customized by changing the arm length and finger length.

## Outside dimensions





### ■ RR491/RR492 (common section)

