Vacuum Robot

RR491/RR492 SERIES

The RR491/RR492 frog leg arm vacuum robot realizes high positioning repeatability and highly reliable vacuum partition performance by adopting DDM (vacuum direct drive motor) for the drive section. The full-link arm mechanism realizes highly accurate positioning repeatability.



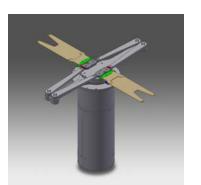


Image: RR491L300

Image: RR492L400

Features

High accuracy

•Corresponding to ultrahigh vacuum

Work size to be handled

High throughput

•Corresponding to the AWC option (wafer position compensation)

Main specifications (RR491)

Main specifications (RR492)

_400 φ 980

1030 mm

70 mm or 140 mm

300 mm works, 200 mm works, and 150 mm works

Work size to be handled

300 mm works, 200 mm works, and 150 mm works

Operating range

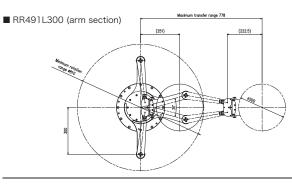
Operating range		Operating range	
Arm length	L300	Arm length	
Minimum rotation range	φ 810	Minimum rotation range	
Distance of reached work	770 mm	Distance of reached work	
center Note 1	770 11111	center Note 1	
Z-axis	70 mm or 140 mm	Z-axis	

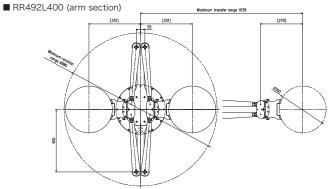
Repeatability

R direction	± 0.05 mm	R direction	± 0.05 mm	
θ direction	± 0.03°	θ direction	± 0.03°	
Z direction	± 0.05 mm	Z direction	± 0.05 mm	

Note 1: The distance of reached work center can be customized by changing the arm length and finger length.

Outside dimensions



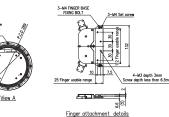


12-#9 though-hol 12-#14 depth 8.6

0-ring Face Inside of \$27

■ RR491/RR492 (common section)







Vacuum Platform

18 RR491/RR492 SERIES RR491/RR492 SERIES